

The Science of Speed: from GAIT MOTION to GROUND FORCE



***Gambetta Athletic
Improvement Network***

*Houston, TX
June 13, 2018*

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Southern Methodist University
Dallas, Texas, USA



Vern Gambetta



Dr. Ken Clark

GAIN 2018

Hopes, Aspirations & 1st Appearances

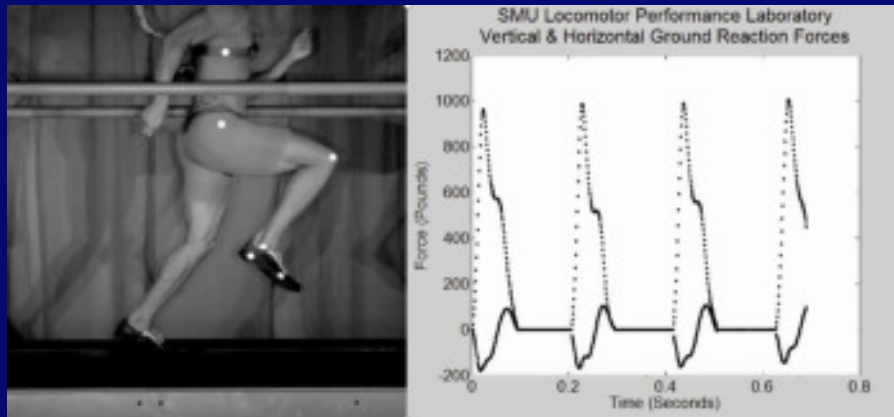
Vern Gambetta



GAIN 2018

BACK TO BASICS

The Science of Speed: from GAIT MOTION to GROUND FORCE

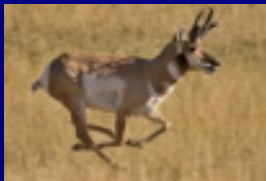
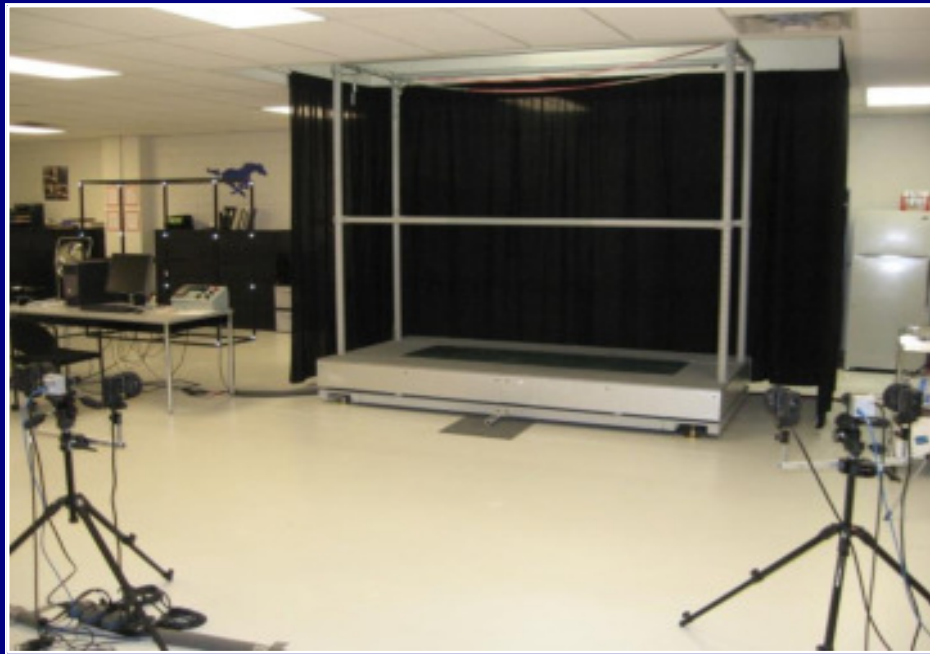


SMU Locomotor Performance Laboratory



YOUTUBE: locomotorlabsmu

TWITTER: @Dr_Weyand

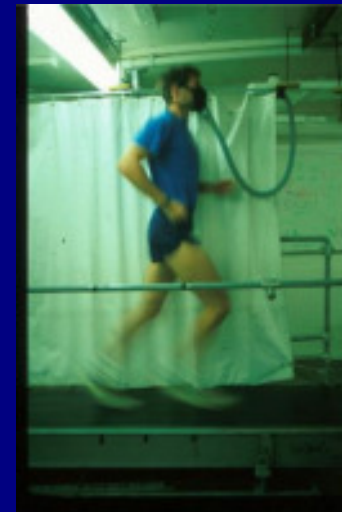
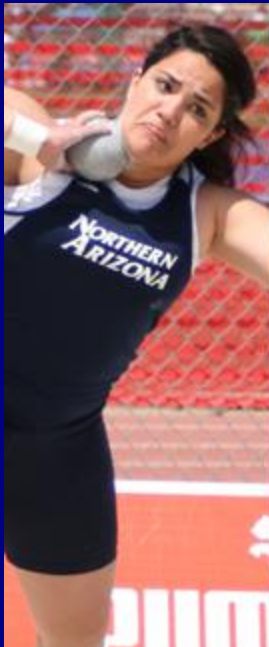


Science Chronology:

Cowboy Science from Harvard to Heart of Texas



Speed Research: Background & Origins



Cowboy Science with Ivy League Roots:

Force-Motion-Energy: Locomotion and Movement

Harvard University
Concord Field
Station



Locomotor performance - approaches & perspectives

C. Richard Taylor
(1940 – 1995)



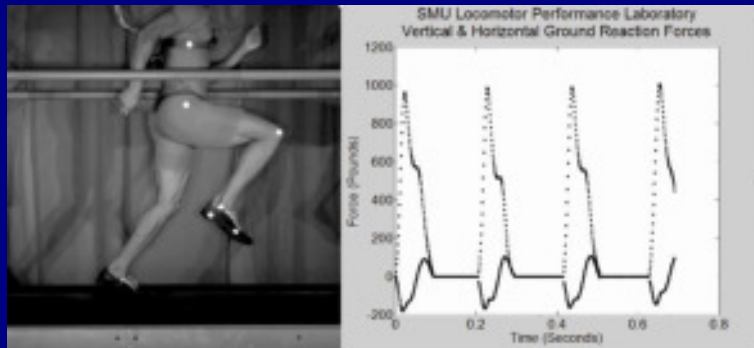
Chronology, Funding, Talent



SMU/LPL



Harvard U/CFS



Origins of Sprinting Research



Faster top running speeds are achieved with greater ground forces not more rapid leg movements

PETER G. WEYAND, DEBORAH B. STERNLIGHT,
MATTHEW J. BELLIZZI, AND SETH WRIGHT
*Concord Field Station, Museum of Comparative Zoology,
Harvard University, Bedford, Massachusetts 01730*

Received 30 March 2000; accepted in final form 14 September 2000

Greyhounds or Humans???



Study Design:

Test slow, medium, fast runners (n=33)

Faster top running speeds are achieved with greater
ground forces not more rapid leg movements

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Two Speed Questions

Faster top running speeds are achieved with greater ground forces not more rapid leg movements

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1) What limits running speed?

2) What determines differences in top speed?

Two Speed Questions

Faster top running speeds are achieved with greater ground forces not more rapid leg movements

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2) What determines differences in top speed?

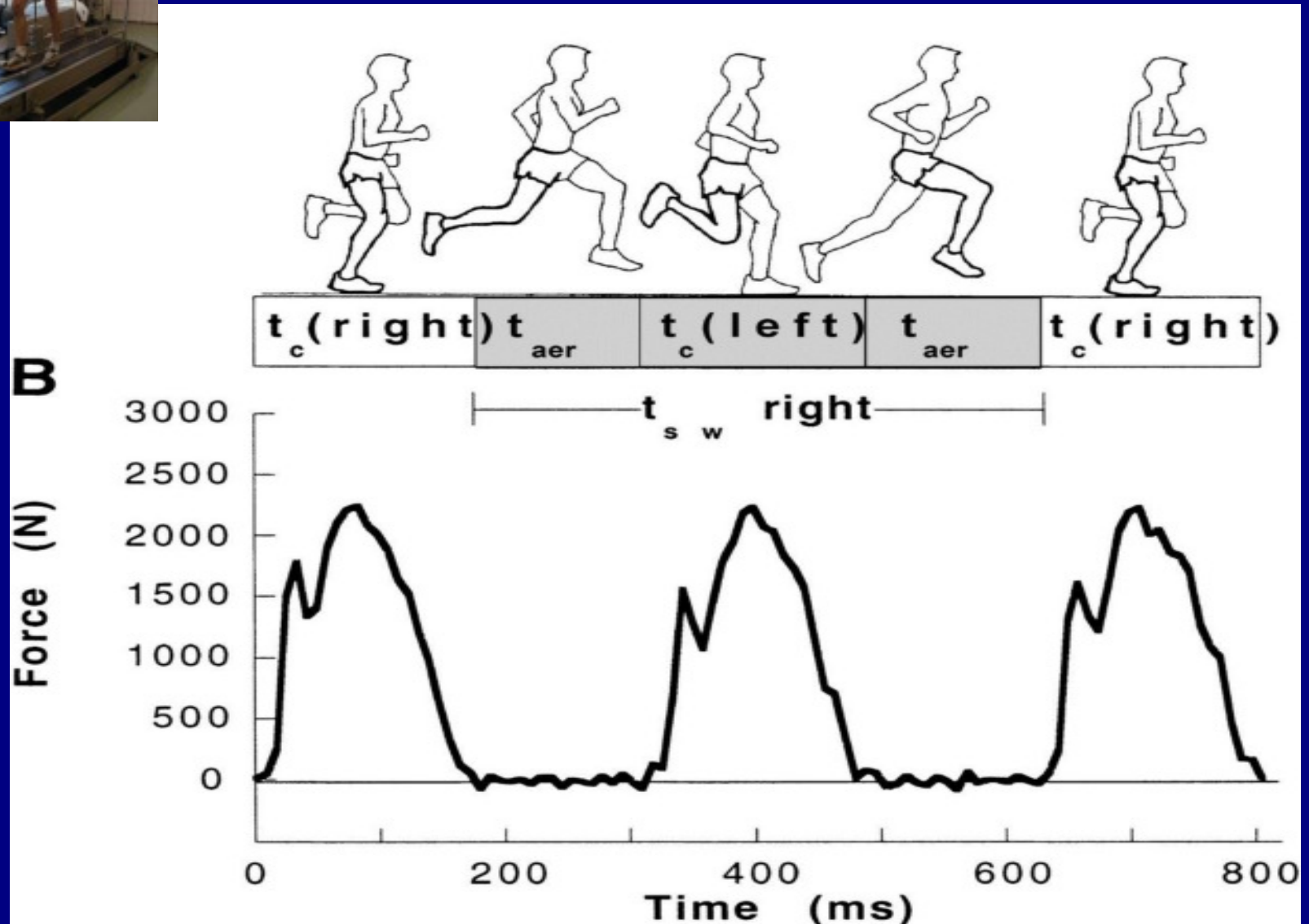
Treadmill Sprint Test $[n=33]$

(> 26 mph)

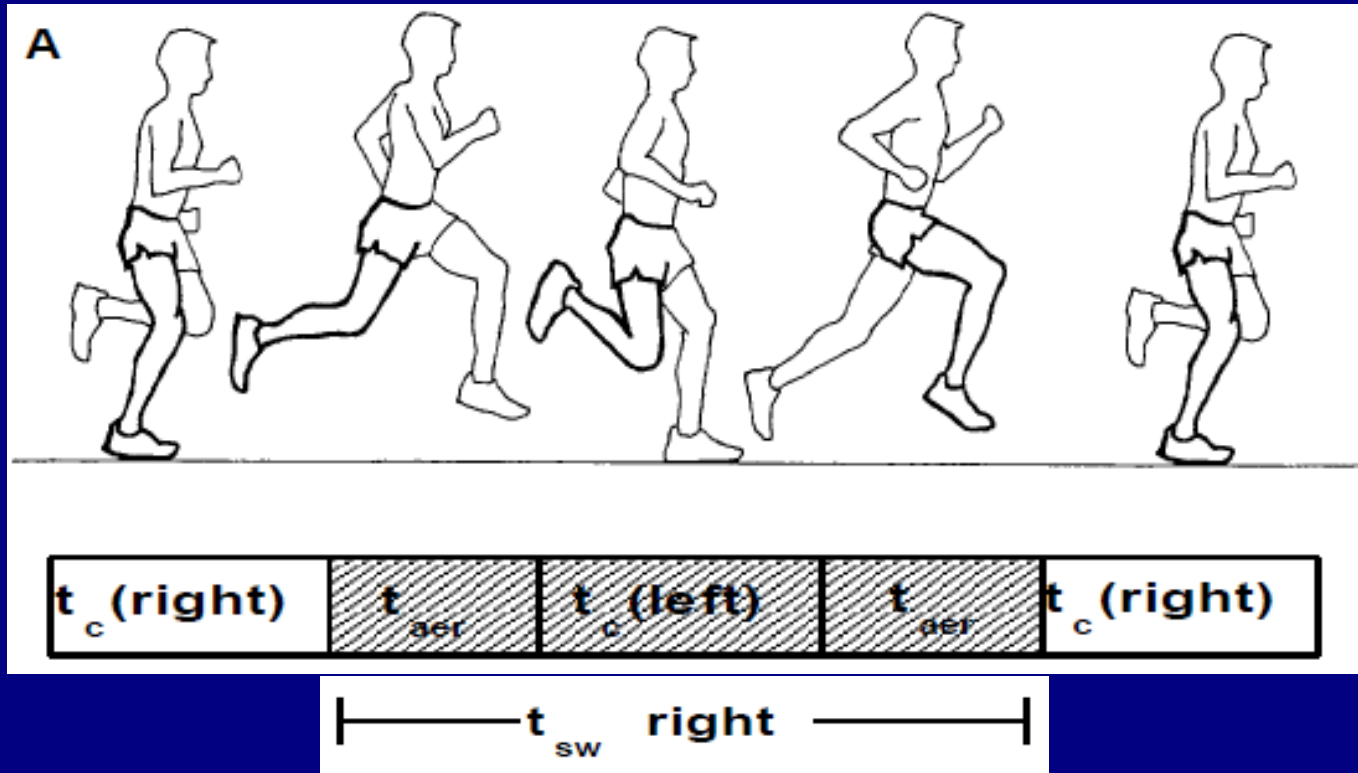




Force Treadmill Data



Human Running Stride



CONTACT (t_c), AERIAL (t_{aer}), SWING (t_{sw})

BASIC CONCEPT

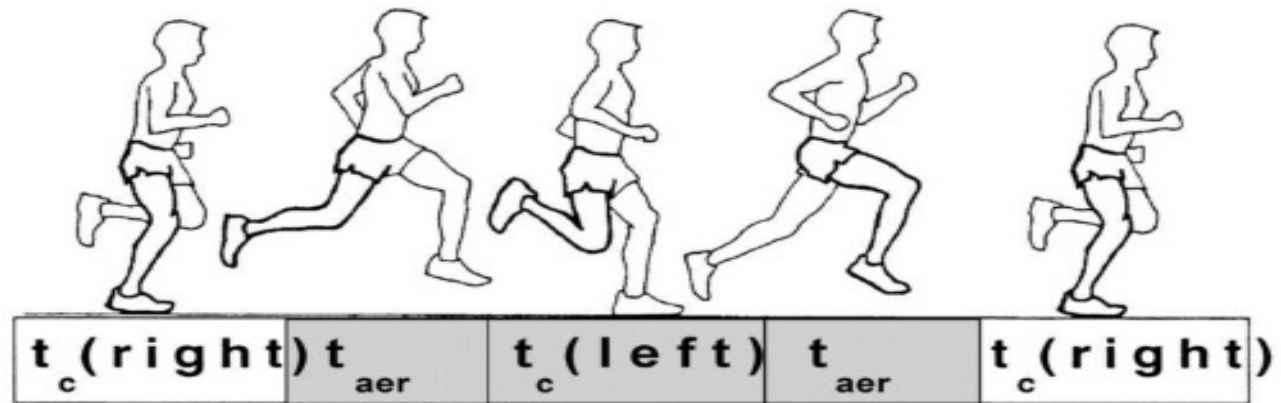
The mechanical requirement of running is:



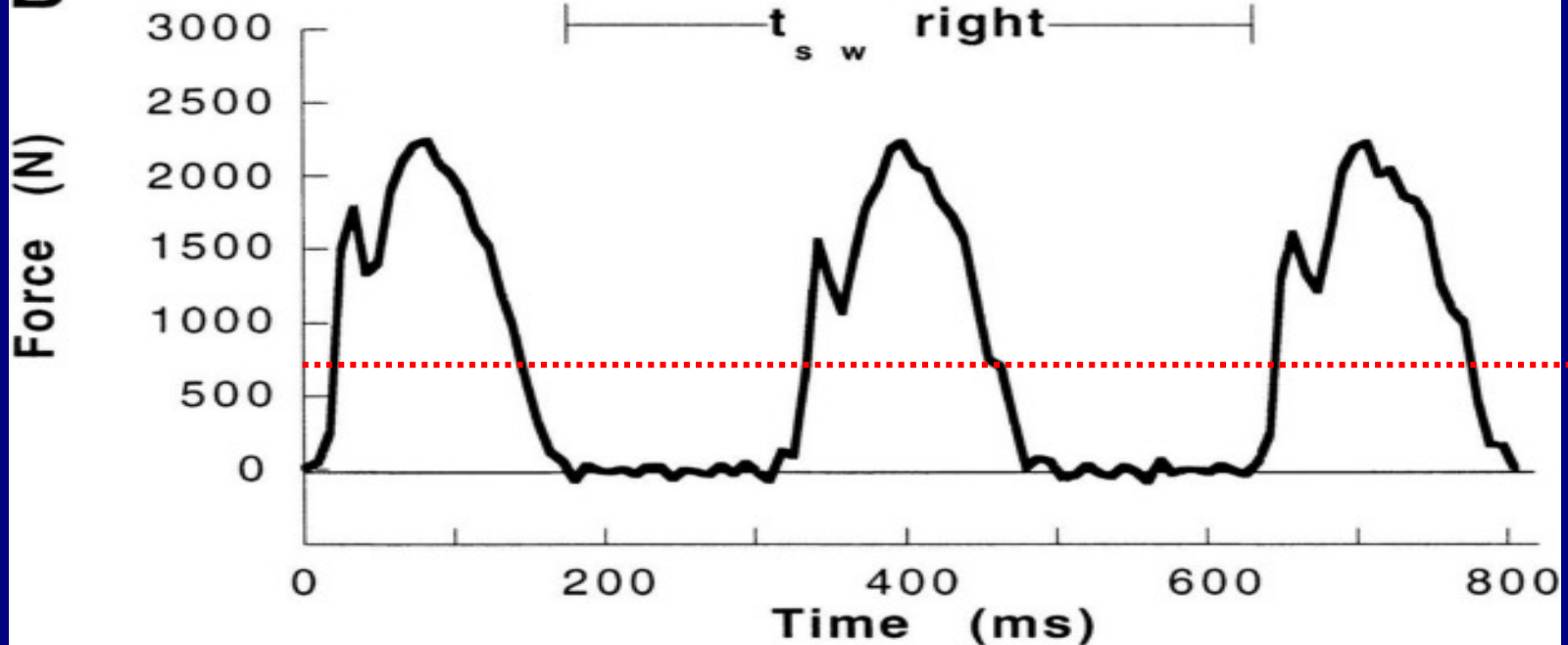
Applying ground force to support body weight



Force Treadmill Data



B



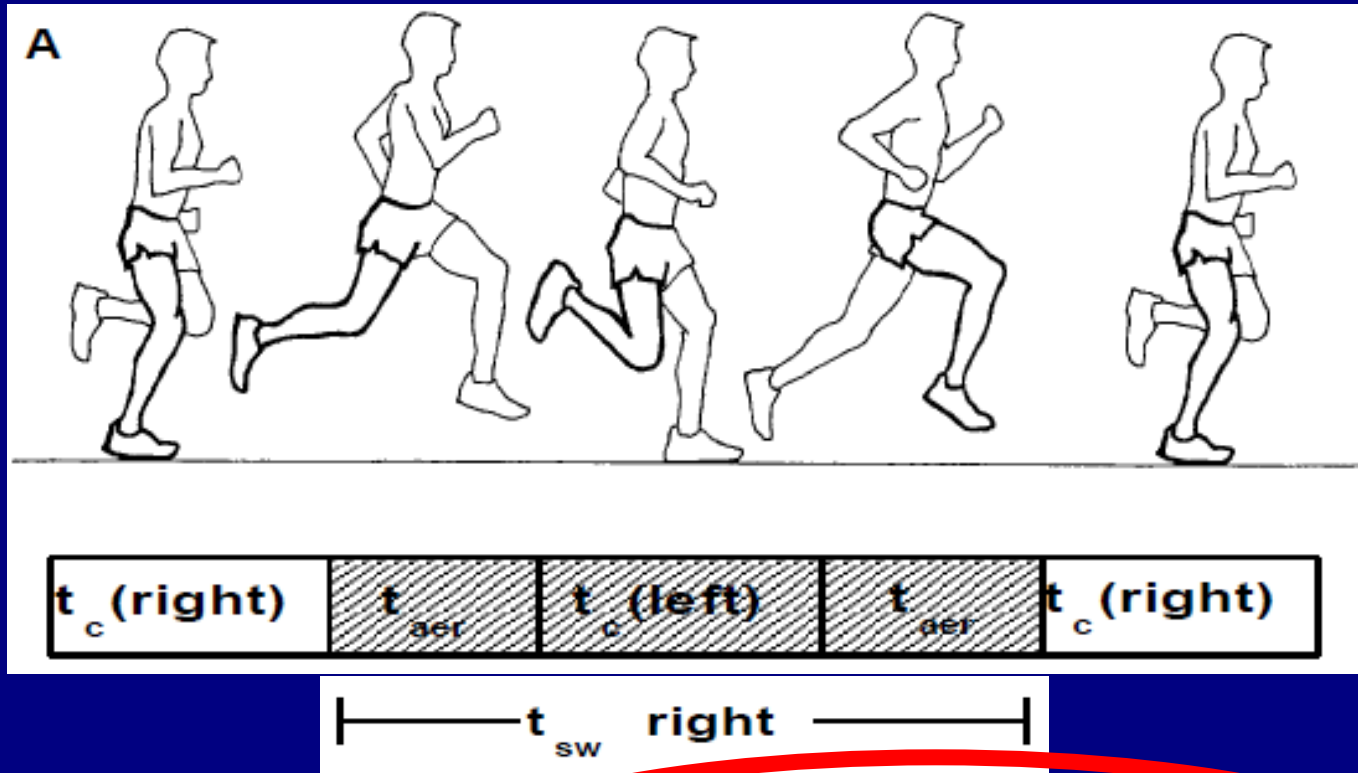
Results

SCIENTIFIC PUNCH LINE #1



The timing of the human running stride is highly constrained

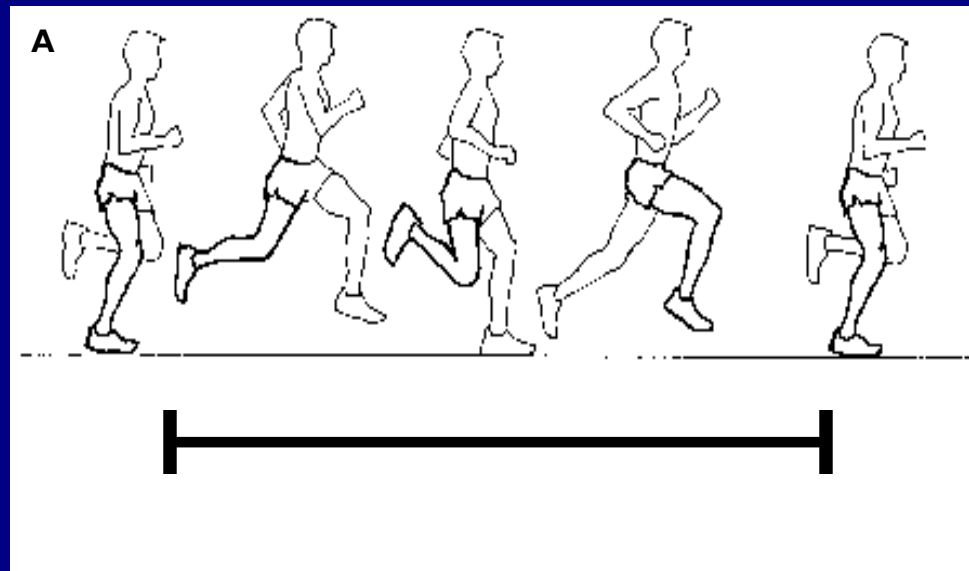
Human Running Stride



CONTACT (t_c), AERIAL (t_{aer}), SWING (t_{sw})

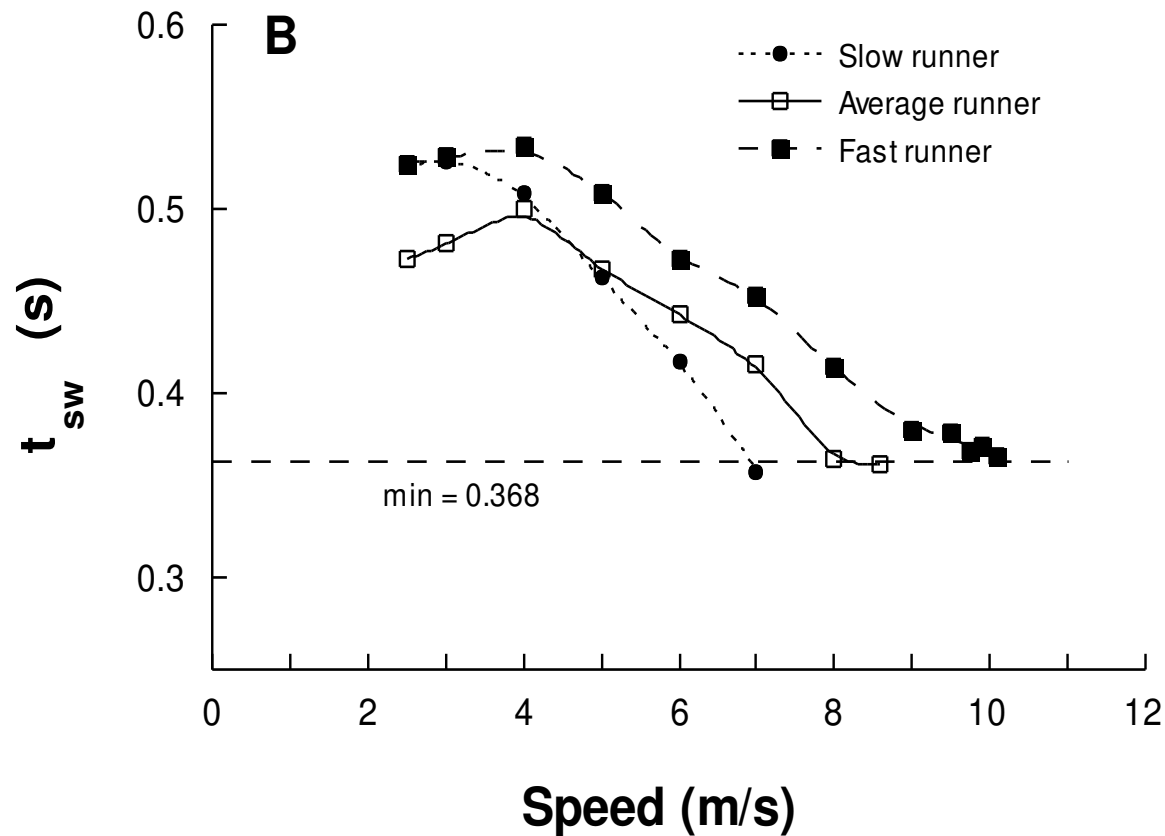
Swing time

(or limb repositioning time)

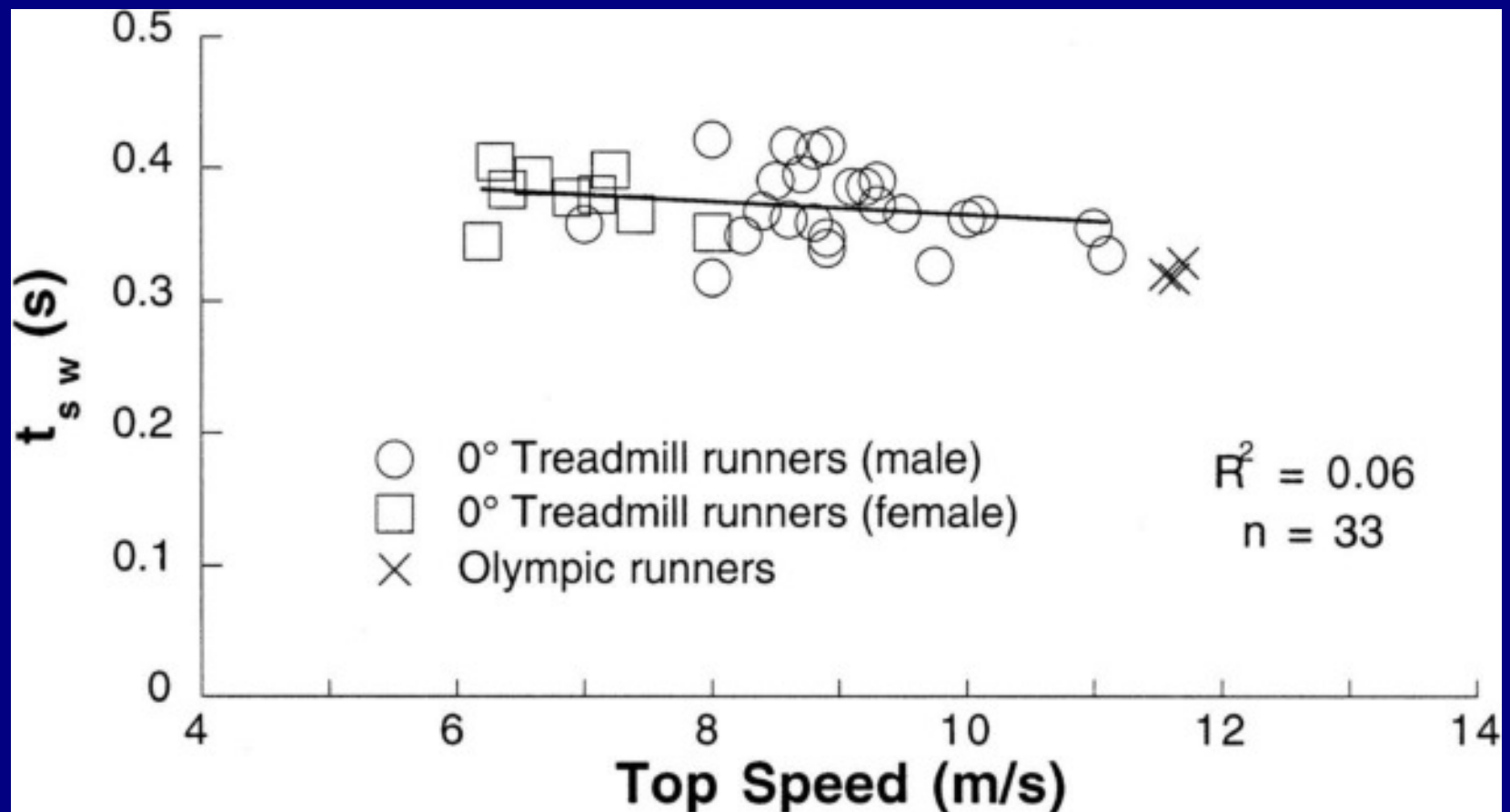
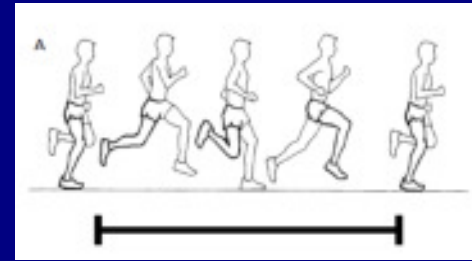


Swing times across speed

Real Data – Three runners (n=3)



Limb Swing times at top speed ($n=33$)



Swing times

Sprinter vs. Non-sprinter



Olympic Sprinter
23.0 mph

Athlete Non-Sprinter
19.0 mph

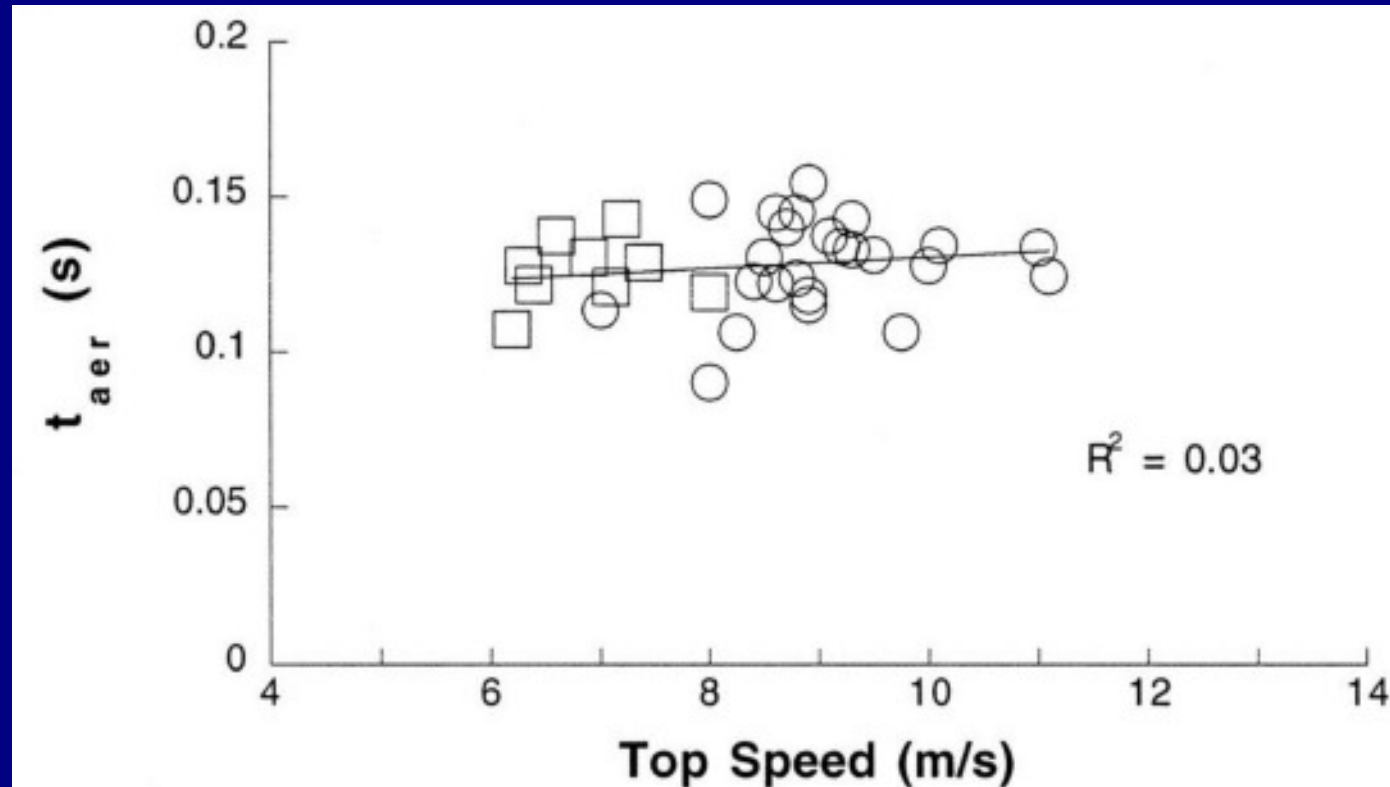
Punch Line #1

SAME SWING TIMES



Usain to slow pokes

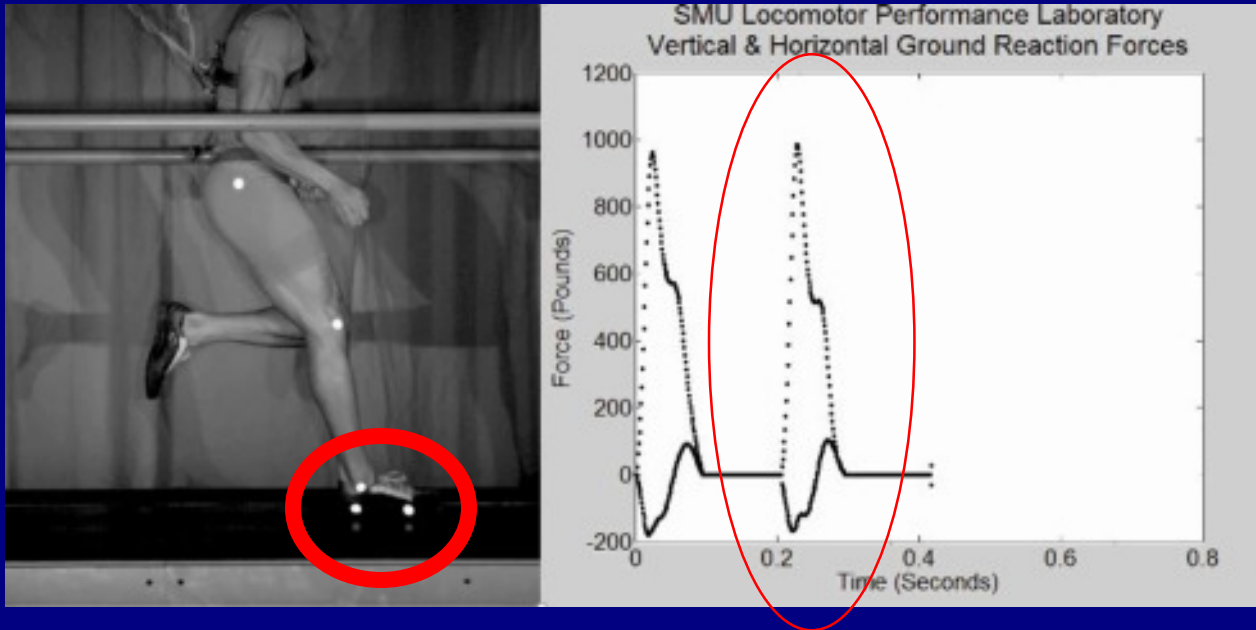
Aerial Time at top speed (n=33)



**If swing times are similar,
what confers fast sprint speeds?**

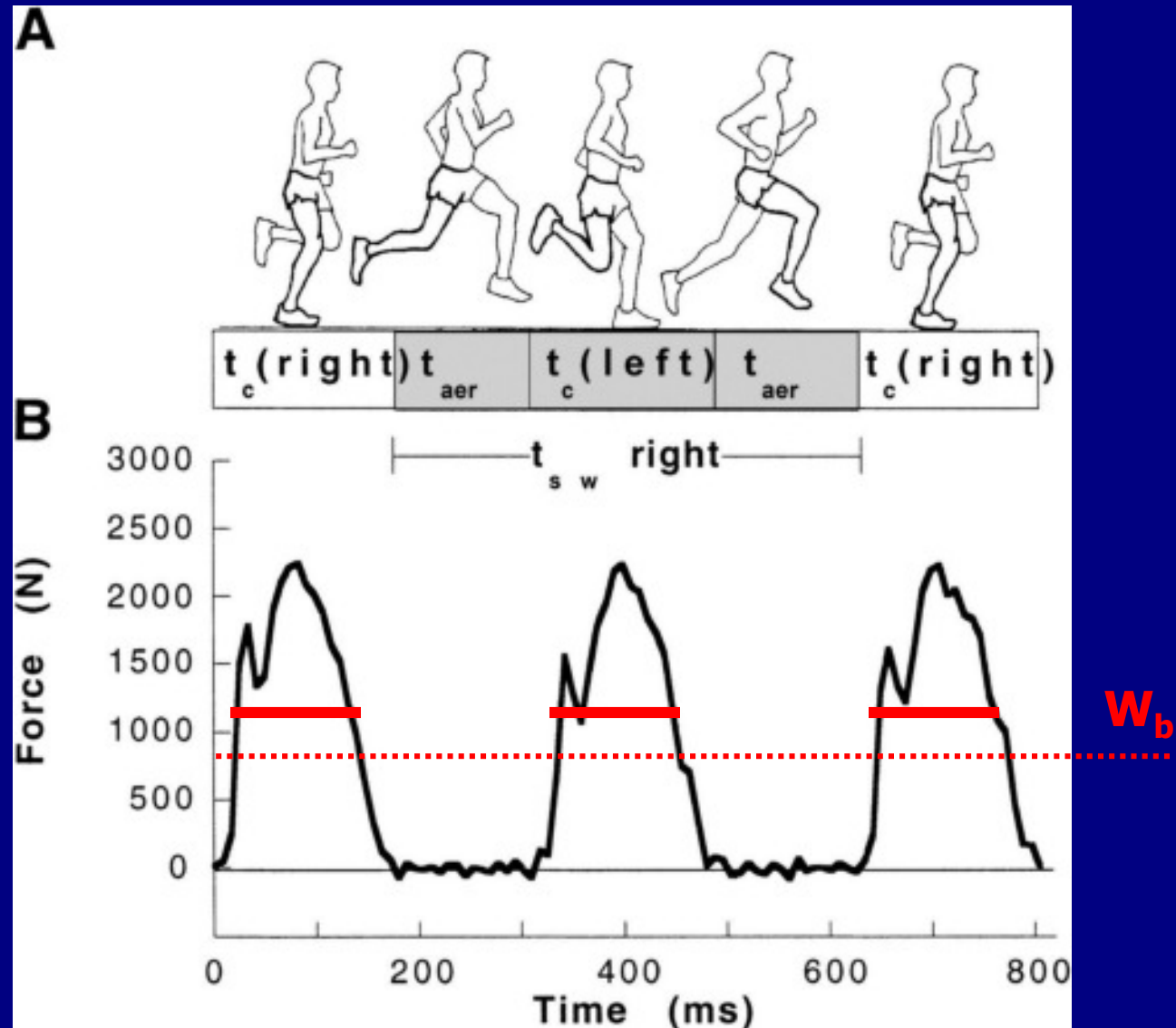


SCIENTIFIC PUNCH LINE #2



Big ground forces - the how of fast speeds
(Peak 5 x body weight)

Force Treadmill Data



Relative
FORCE

into the ground
(x Body Weight)

Jog =
1.5 X Body Weight

(Everyone)

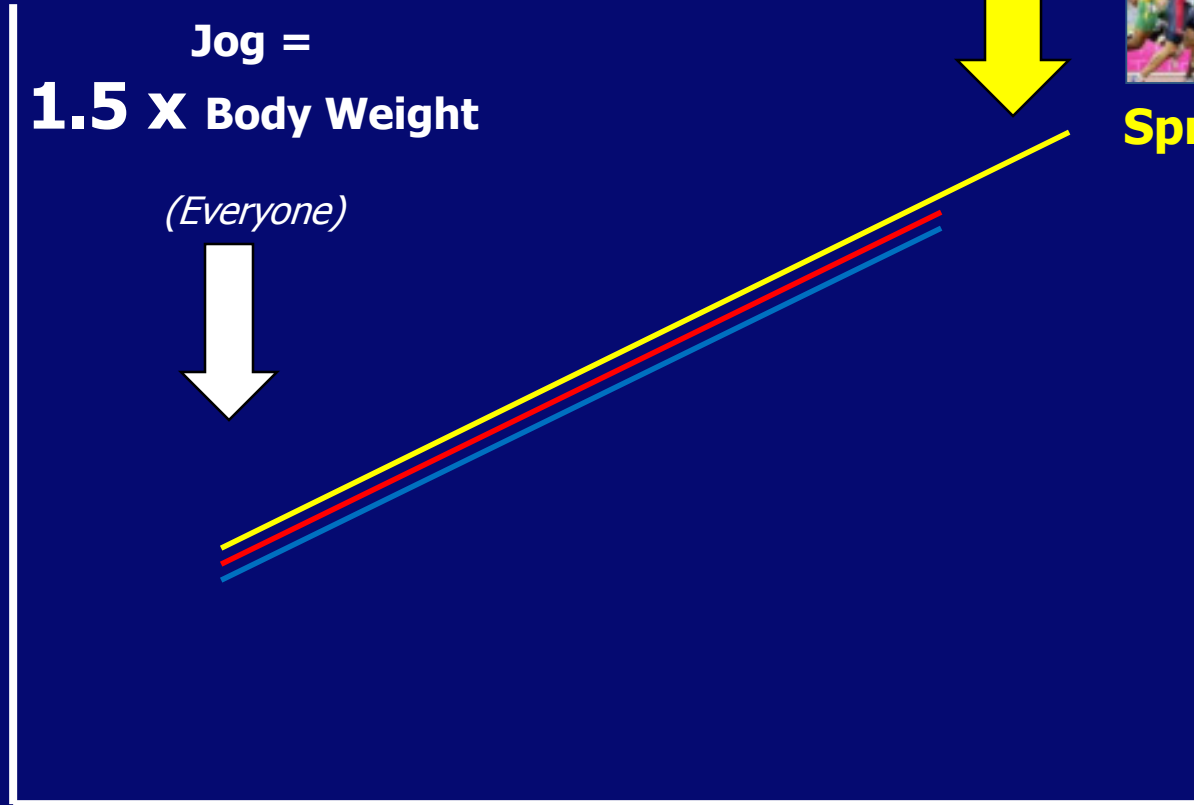


Elite Sprint =
2.5 X Body Weight



Sprinter

SPEED



Force vs. speed relationship - general

$$\text{Force} = 1.26 W_b + 0.1 W_b \bullet \text{Velocity}$$

Faster top running speeds are achieved with greater ground forces not more rapid leg movements

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At top speed:

- different runners

The biological limits to running speed are imposed from the ground up

Peter G. Weyand,^{1,2} Rosalind F. Sandell,^{1,2} Danille N. L. Prime,² and Matthew W. Bundle³

¹Department of Applied Physiology and Wellness, Southern Methodist University, Locomotor Performance Laboratory, Dallas, Texas; ²Kinesiology Department, Locomotion Laboratory, Rice University, Houston, Texas; and ³Biomechanics Laboratory, College of Health Sciences, University of Wyoming, Laramie, Wyoming

Across speed:

- individual runners

Fast Runners:

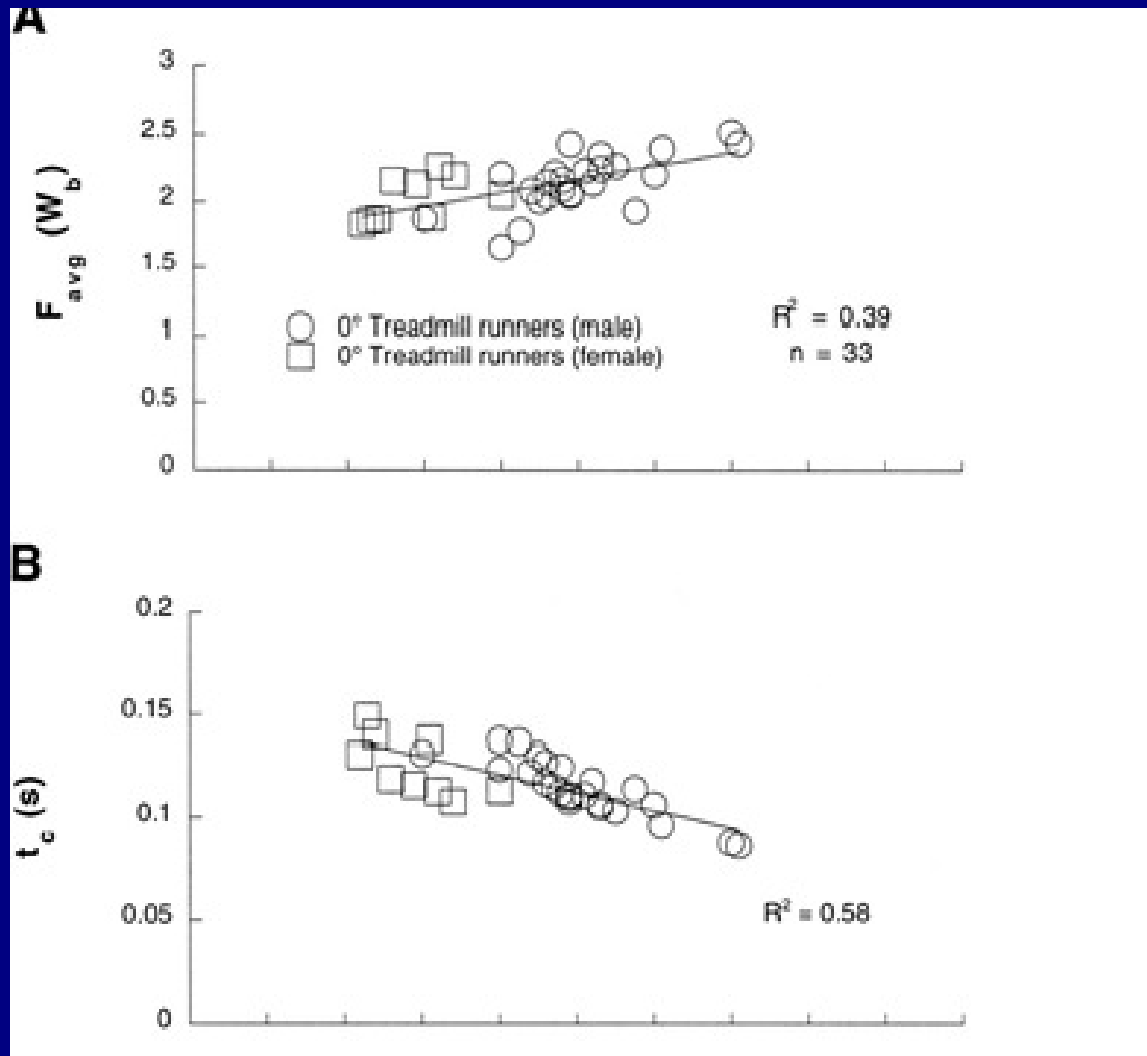


- 1) Apply large ground forces (Force/mass)
- 2) Have short contact times

Mechanics of ground force application determine speed

Force
(W_b)

t_c
(s)



FAST

More
force

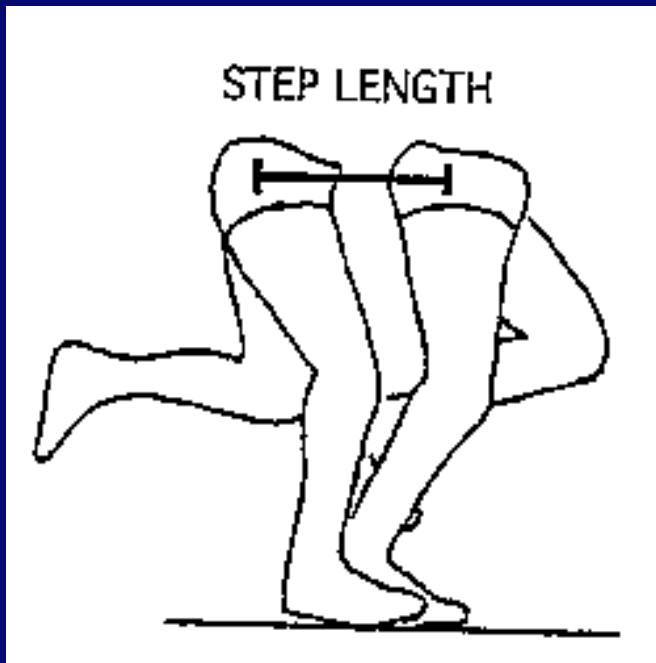
Shorter times
of force
application

Top Speed (m/s)

Contact Times ~ must decrease as Speed Increases

Step length (L_c):

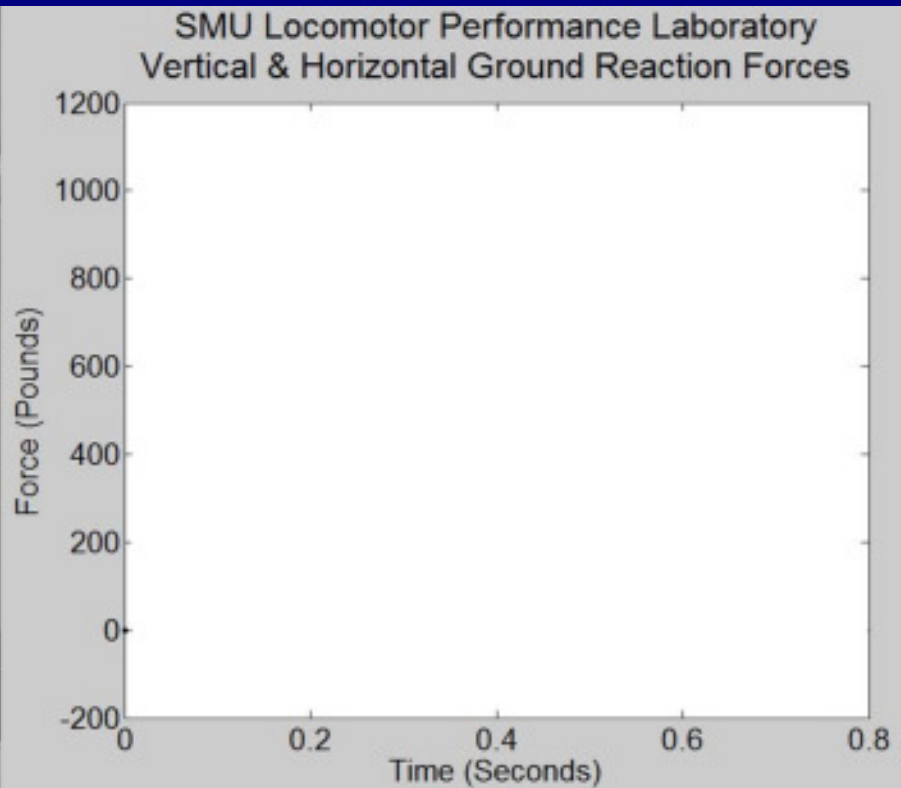
1.0 meter



Speed (m/s)	Contact Time (s)
1.0	1.00
2.0	0.50
4.0	0.25
10.0	0.10

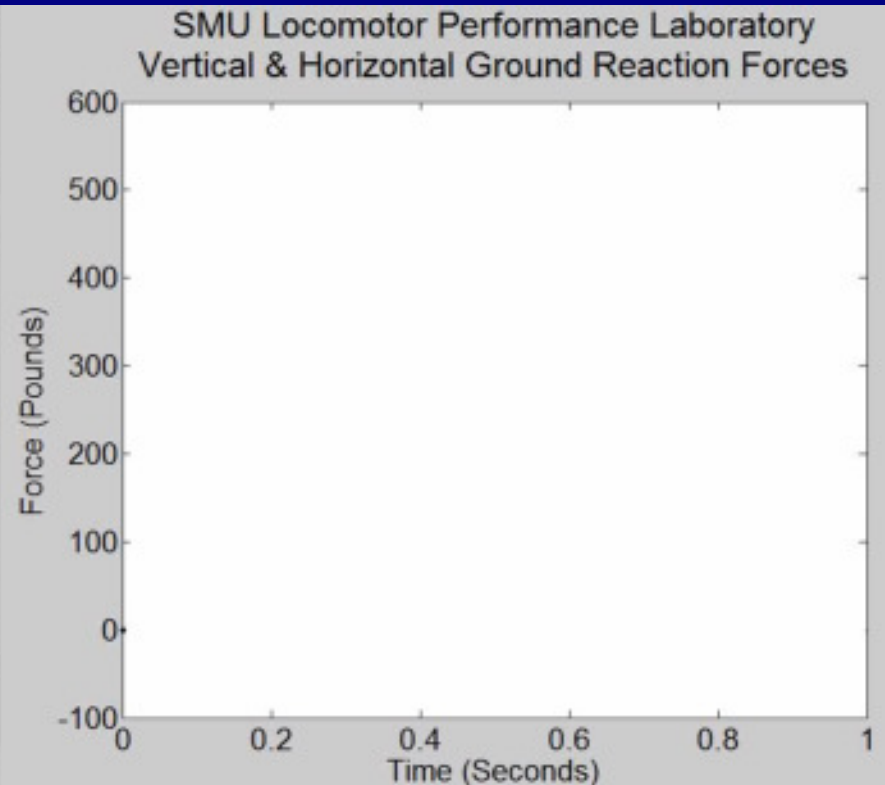
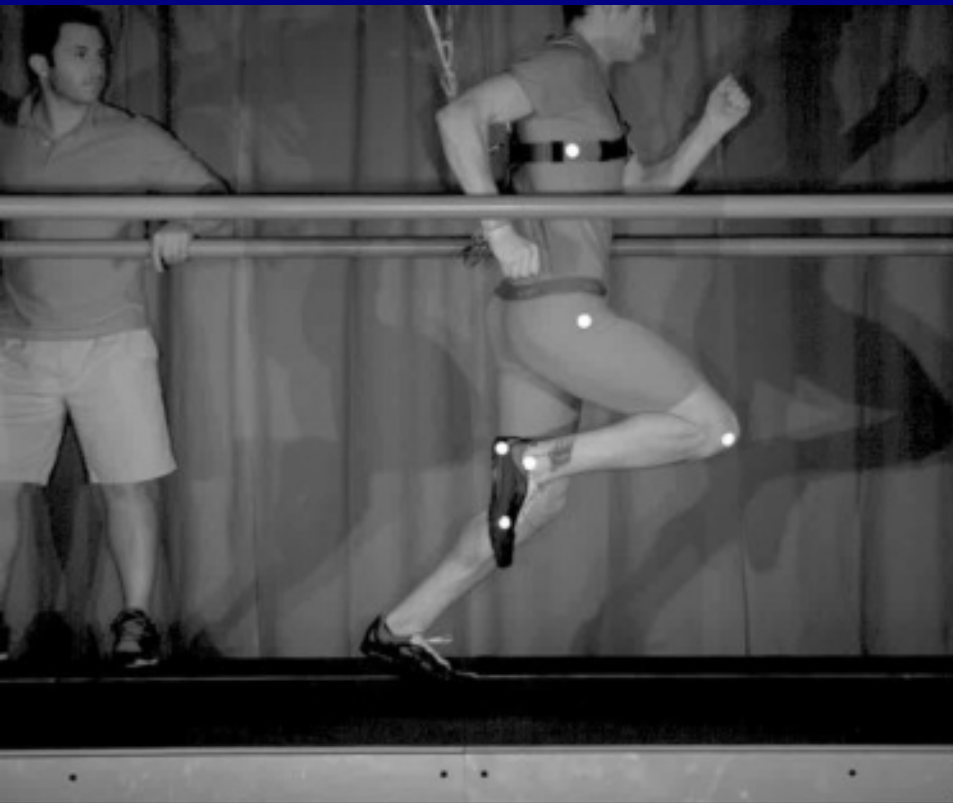
L_c changes little from moderate to top sprint speeds

Sprinters hit the ground forcefully (*Force/mass*)



BIG FORCES
Distinct Waveform Shape

Middle Distance Runner



Less force/mass

PART 3

How do faster runners hit the ground more forcefully?



What is THE SECRET?

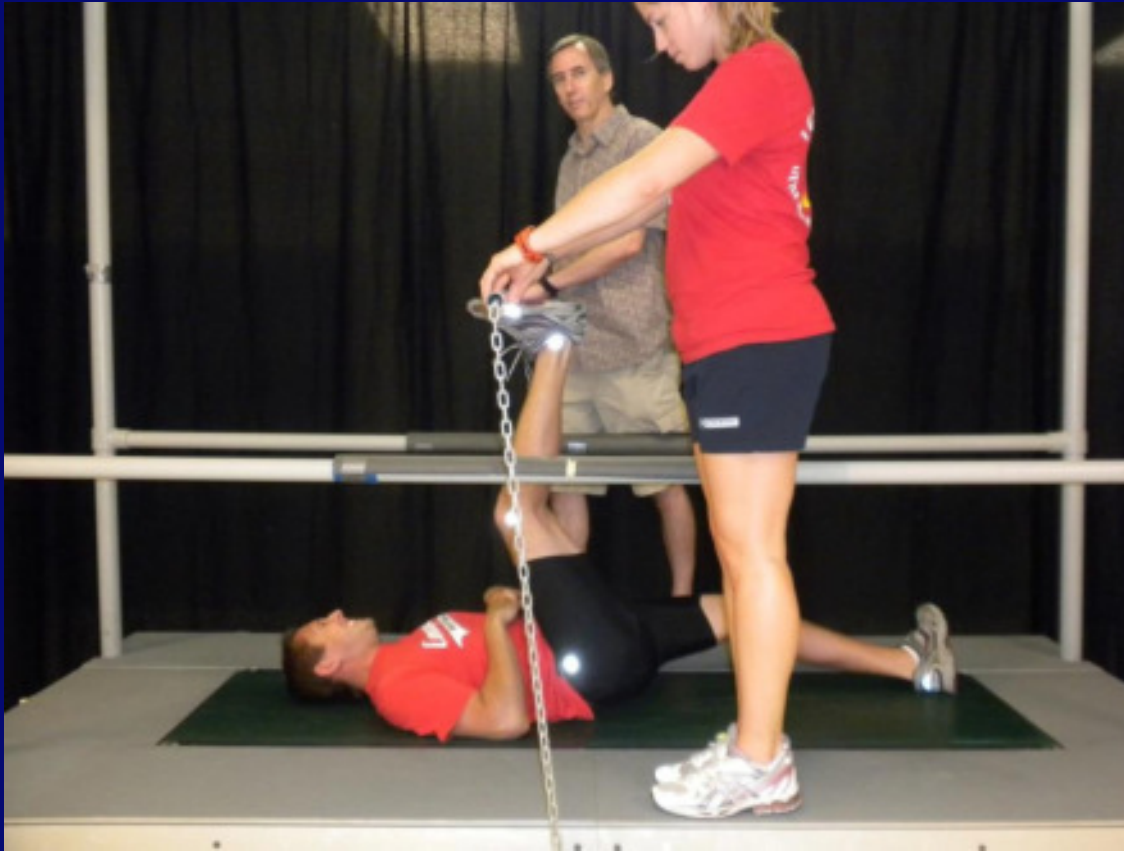
DEBATE:

What is THE SECRET?



Limb strength or running form?

Strength or Gait Mechanics?



How do the Fastest Runners Hit the Ground More Forcefully?

Limb Motion-Force



**THEY ATTACK
THE GROUND**

Motion to force mechanism



Ken Clark, Ph.D.
Doctoral Student



Larry Ryan, Ph.D.
Physicist

Same time, different motion

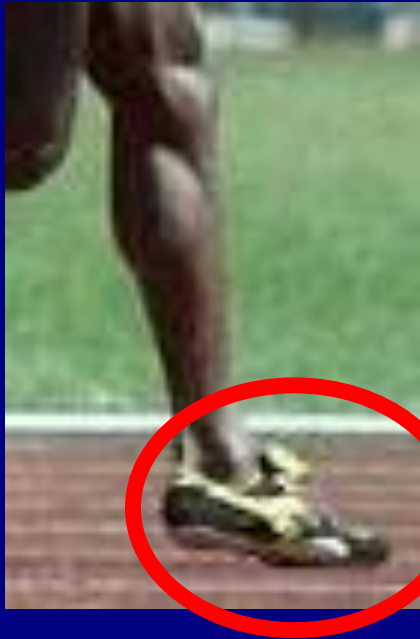
Sprinter vs. Non-sprinter



Olympic Sprinter
23.0 mph

Athlete Non-Sprinter
19.0 mph

SCIENTIFIC PUNCH LINE #3



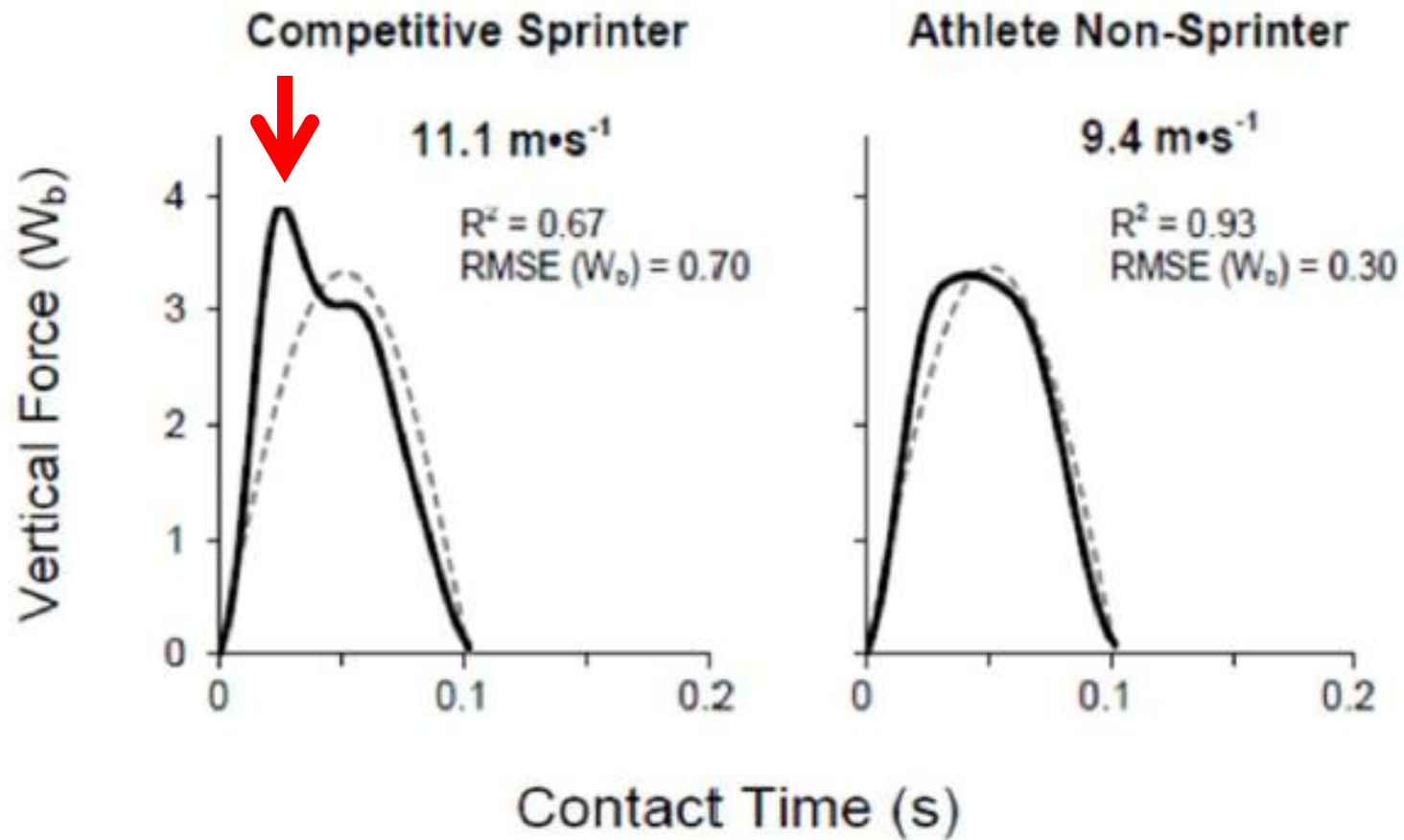
- **FAST LEG VELOCITY**
- **QUICK STOP**



Big forces from: big deceleration on impact

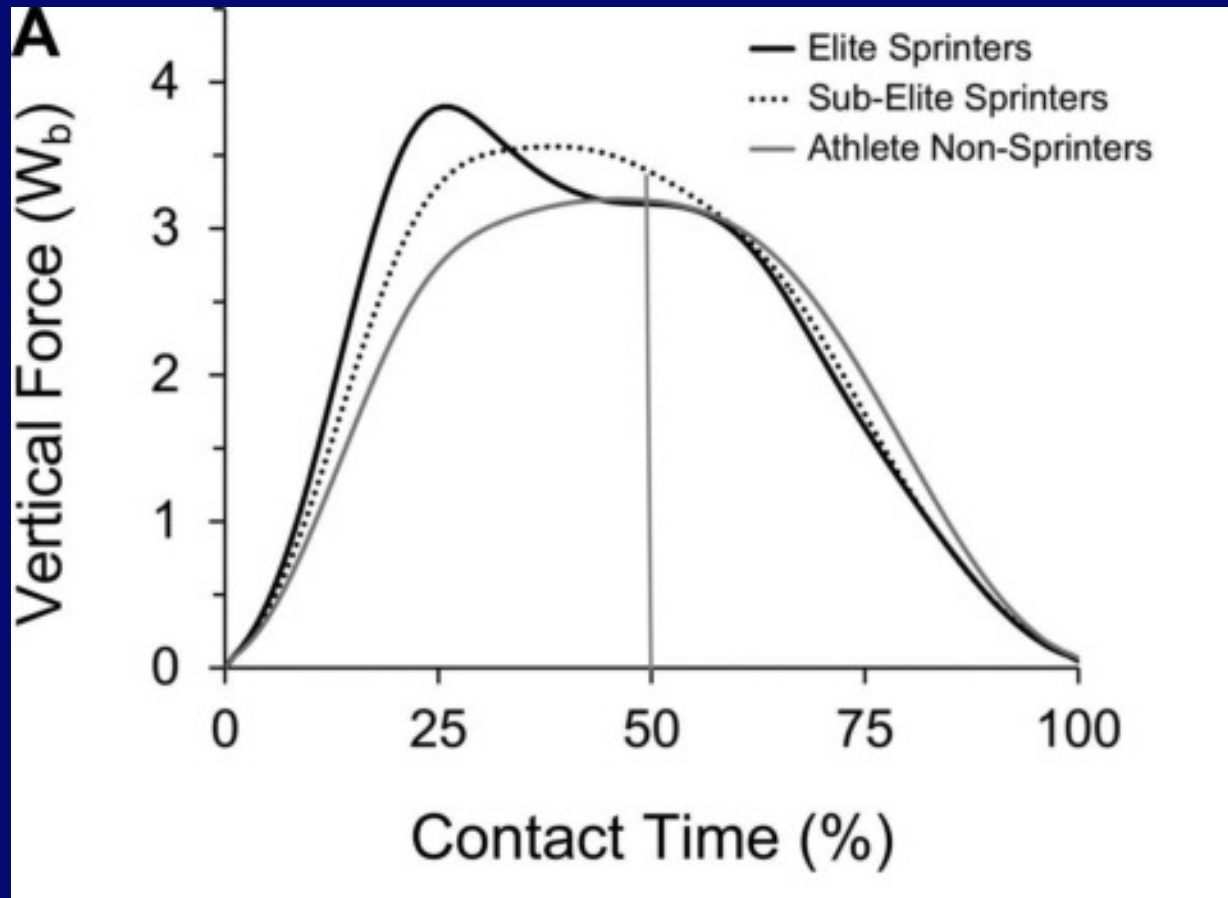
Force-Time Waveforms

Illustrate the Secret to Big Ground Forces

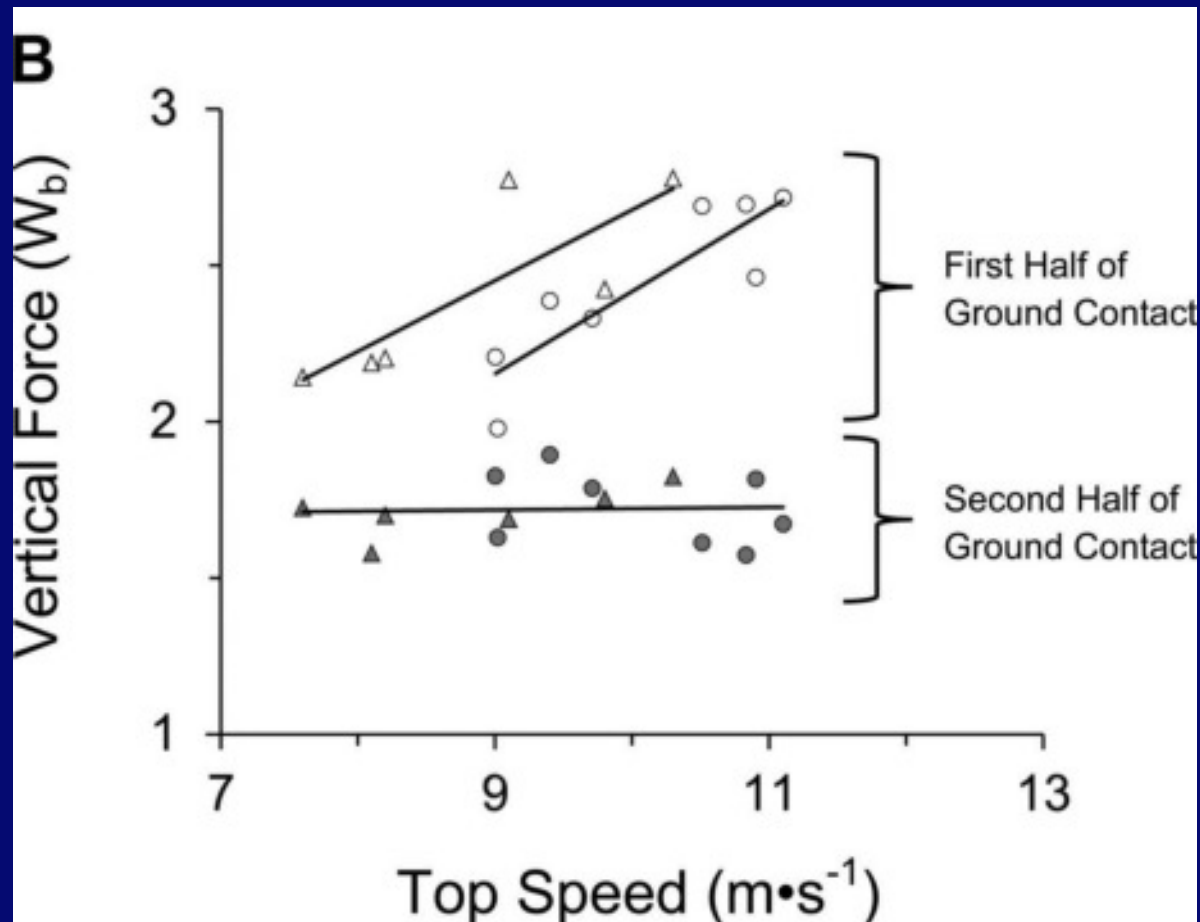


Elite vs. Sub-elite Males

TOP SPEED



Fourteen Athletic Subjects: Top Speed Forces

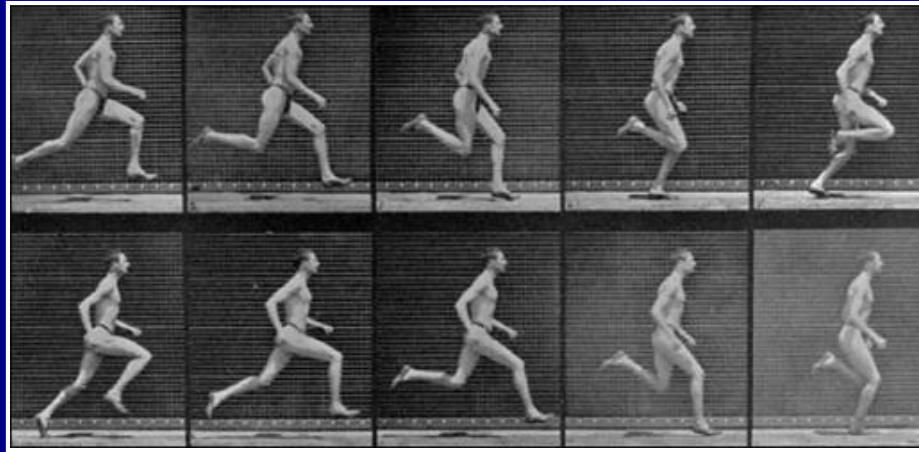


Lower-Limb: Two Critical Actions – Punch Analogy



- 1. Drive it Fast**
- 2. Stop it quick**

Musculoskeletal Biology & Physics ➡ Speed



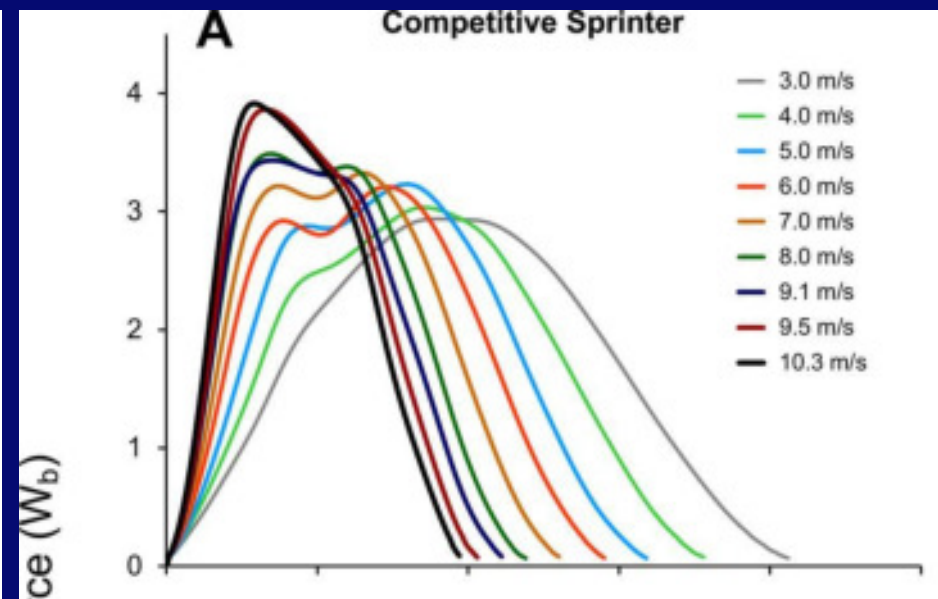
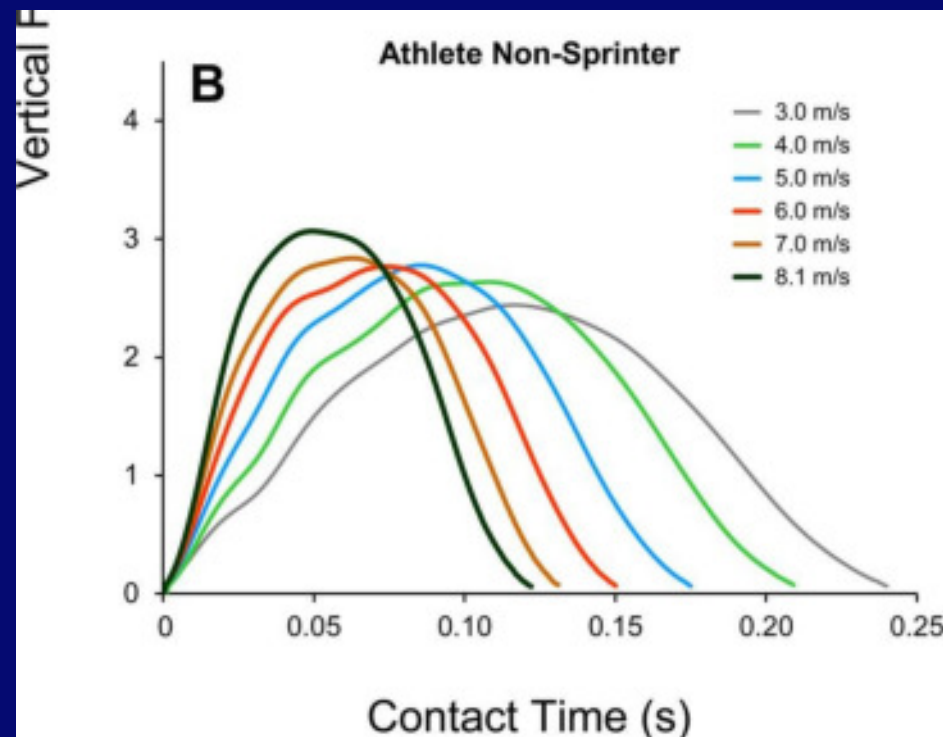
Convergence on a Single Solution



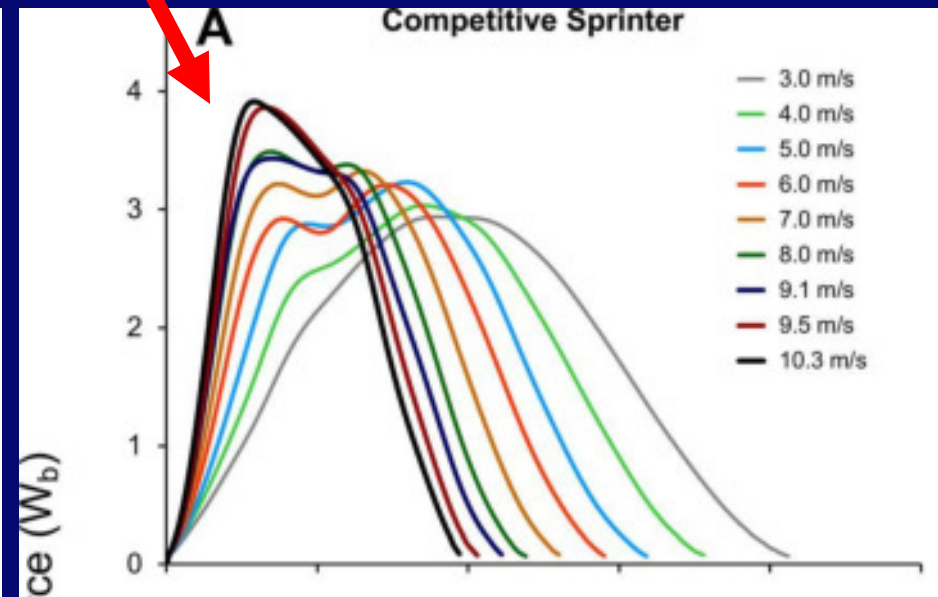
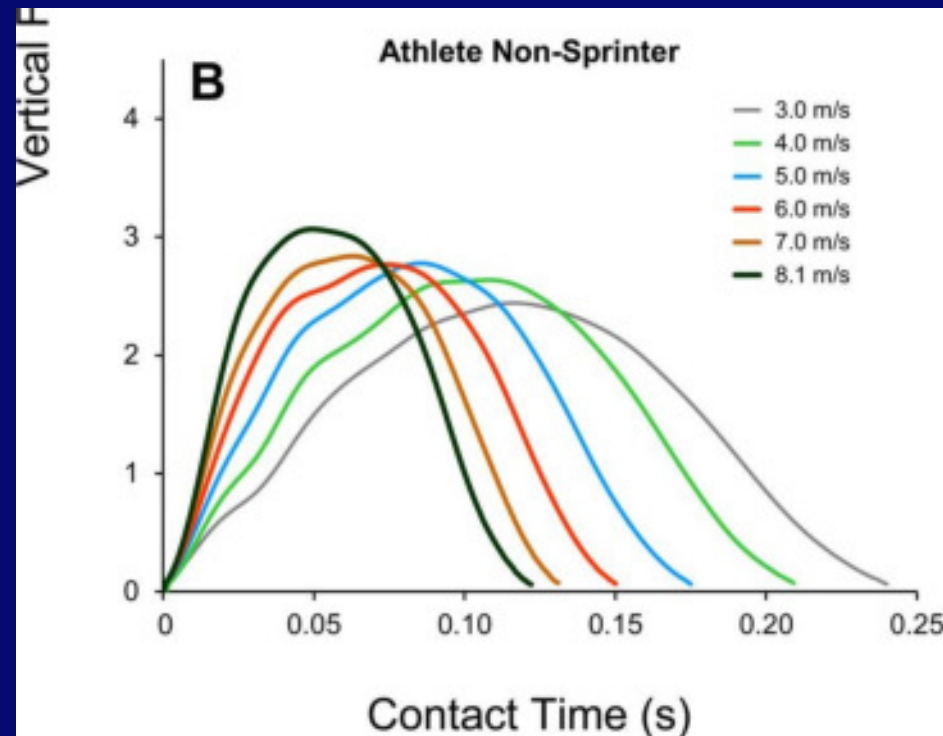
Gait Modification for Speed

Sprinters Attack the Ground:

Force-time patterns at different speeds



Sprinters Attack the Ground





Chair demo



Shoe demo

Same time, different motion

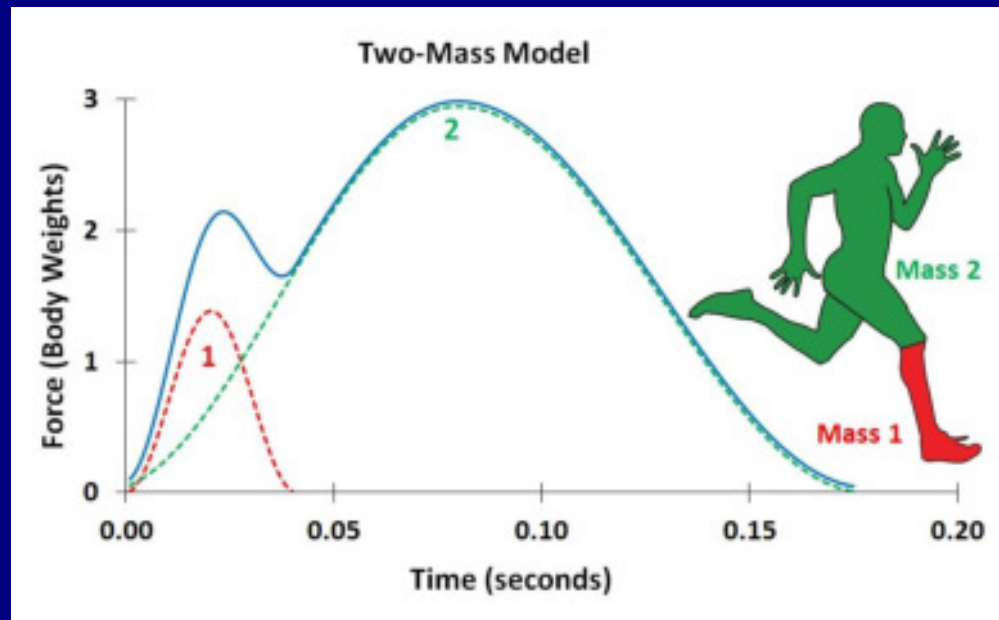
Sprinter vs. Non-sprinter



Olympic Sprinter
23.0 mph

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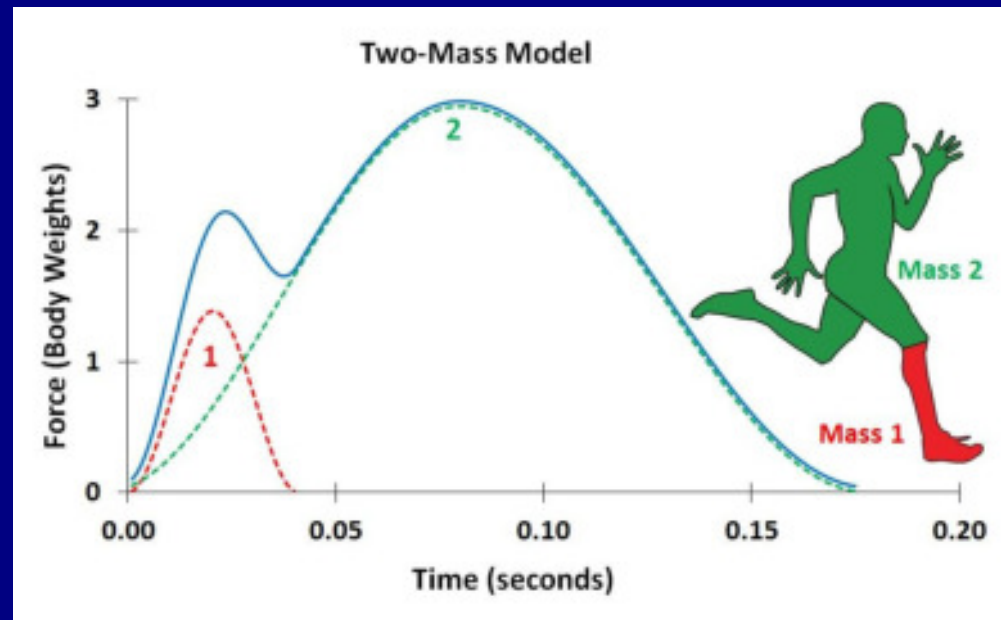
Two-Mass Model: The general link: motion and force during running



Three Inputs: 1) Contact time, 2) aerial time, 3) ankle motion

Two-mass Model: Attacking the Ground

Two-Mass Model: The general link: motion and force during running



Three Inputs: 1) Contact time, 2) aerial time, 3) ankle motion

Motion to Force Applications: Two-Mass Model

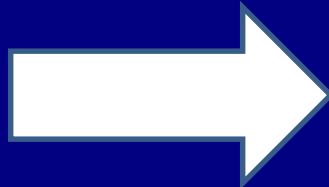
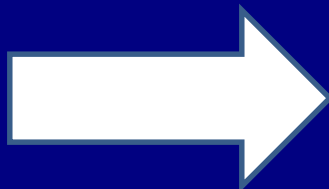
MOTION



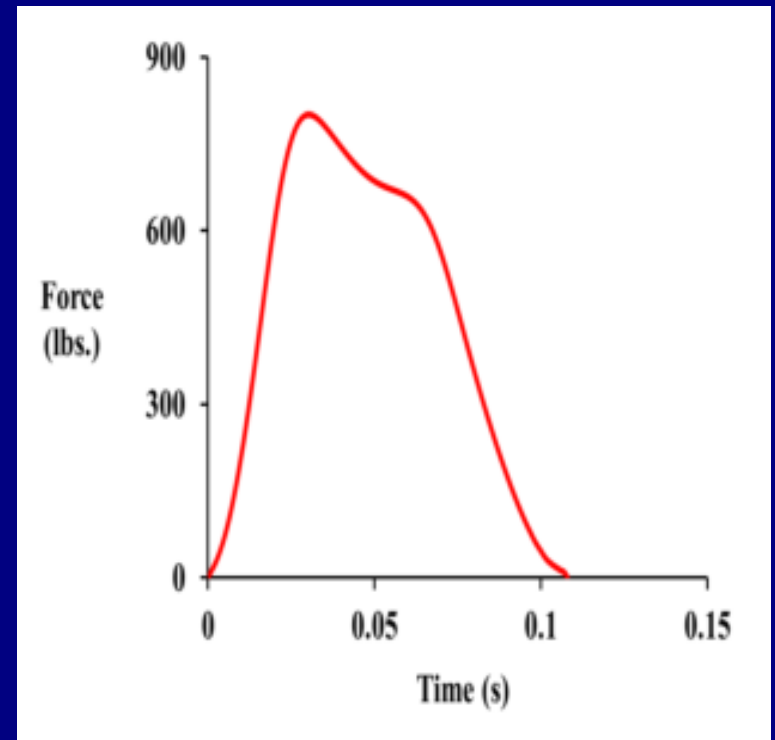
Video



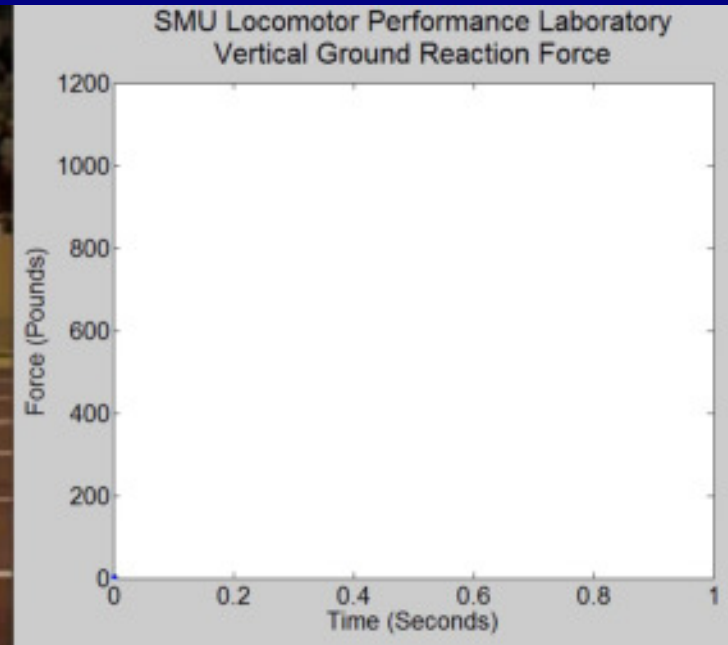
Sensors



FORCE



So What?



From Motion to Force
(contact time, aerial time, ankle velocity)



- 1) Top Speed swing & aerial times: *NOT DIFF*
- 2) Faster athletes: *GREATER FORCE/MASS*
- 3) Big ground forces: *IMPACT DECELERATION*